Capacity Limits and Multiplexing Gains of MIMO Channels with Transceiver Impairments
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Abstract—The capacity of ideal MIMO channels has an high-SNR slope that equals the minimum of the number of transmit and receive antennas. This letter shows that physical MIMO channels behave fundamentally different, due to distortions from transceiver impairments. The capacity has a finite upper limit that holds for any channel distribution and SNR. The high-SNR slope is thus zero, but the relative capacity gain of employing multiple antennas is at least as large as for ideal transceivers.

Index Terms—Channel capacity, high-SNR analysis, multi-antenna communication, transceiver impairments.

I. INTRODUCTION

In the past decade, a vast number of papers have studied multiple-input multiple-output (MIMO) communications motivated by the impressive capacity scaling in the high-SNR regime. The seminal article [1] by E. Telatar shows that the MIMO capacity with channel knowledge at the receiver behaves as \( \min(N_t, N_r) \log_2(P) + O(1) \), where \( N_t \) and \( N_r \) are the total number of transmit and receive antennas, respectively, and \( P \) is the signal-to-noise ratio (SNR). The factor \( \min(N_t, N_r) \) is the asymptotic gain over single-antenna channels and is called degrees of freedom or multiplexing gain.

Some skepticism concerning the applicability of these results in cellular networks has recently appeared; modest gains of network MIMO over conventional schemes have been observed and the throughput might even decrease due to the extra overhead [2], [3]. One explanation is the finite channel coherence time that limits the resources for channel acquisition [4] and coordination between nodes [5], thus creating a finite fundamental ceiling for the network spectral efficiency—irrespectively of the power and the number of antennas.

While these results concern large network MIMO systems, there is another non-ideality that also affects performance and manifests itself for MIMO systems of any size: transceiver impairments [5]–[10]. Physical radio-frequency (RF) transceivers suffer from amplifier non-linearities, IQ-imbalance, phase noise, quantization noise, carrier-frequency and sampling-rate jitter/offsets, etc. These impairments are conventionally over-looked in information theoretic studies, but this letter shows that they have a non-negligible and fundamental impact on the spectral efficiency in modern deployments with high SNR.

This letter analyzes the capacity of a generalized MIMO channel with transceiver impairments. We generalize results from [5] and [7] and emphasize the high-SNR behavior, since the capacity has a finite limit and thus is fundamentally different from the ideal case in [1]. The main conclusion is that the classic multiplexing gain is zero, but the relative improvement over single-antenna channels can be even larger for these physical MIMO channels than with ideal transceivers.

II. GENERALIZED CHANNEL MODEL

Consider a flat-fading MIMO channel with \( N_t \) transmit antennas and \( N_r \) receive antennas. The received signal \( y \in \mathbb{C}^{N_r} \) in the classical affine baseband channel model of [1] is

\[
y = \sqrt{P} H x + n,
\]

where \( P \) is the SNR, \( x \in \mathbb{C}^{N_t} \) is the intended signal, and \( n \sim \mathcal{CN}(0, I) \) is circular-symmetric complex Gaussian noise. The channel matrix \( H \in \mathbb{C}^{N_r \times N_t} \) is assumed to be a random variable \( \mathbb{H} \) having any multi-variate distribution \( f_{\mathbb{H}} \) with the normalized gain \( \mathbb{E}(\text{tr}(H^H H)) = N_t N_r \) and full-rank realizations (i.e., \( \text{rank}(H) = \min(N_t, N_r) \)) almost surely—this basically covers all physical channel distributions.

The intended signal in (1) is only affected by a multiplicative channel transformation and additive thermal noise, thus ideal transceiver hardware is implicitly assumed. Physical transceivers suffer from a variety of impairments that are not properly described by [1] [5]–[10]. The influence of impairments is reduced by compensation schemes, leaving a residual distortion that is well-modeled as additive Gaussian noise on the baseband with a variance that scales with \( P \) [7].

Building on the analysis and measurements in [6]–[8], the combined influence of impairments in the transmitter hardware is modeled by the generalized MIMO channel

\[
y = \sqrt{P} H (x + \eta_t) + n,
\]

where the transmitter-distortion \( \eta_t \in \mathbb{C}^{N_t} \) describes the (residual) impairments. This term describes the mismatch between the intended signal \( x \) and the signal actually generated by the transmitter; see the block diagram in Fig. 1.

Under the normalized power constraint \( \text{tr}(Q) = 1 \) with \( Q = \mathbb{E}(xx^H) \) (similar to [1]), the transmitter-distortion is \( \eta_t \sim \mathcal{CN}(0, \Upsilon_t(Q)) \) with \( \Upsilon_t(Q) = \text{diag}(\upsilon_1(Q), \ldots, \upsilon_{N_t}(Q)) \).

The distortion depends on the intended signal \( x \) in the sense that the variance \( \upsilon_n(Q) \) is an increasing function of the signal power \( q_n \) at the \( n \)th transmit antenna (i.e., the \( n \)th diagonal element of \( Q \)). We neglect any cross-correlation in \( \Upsilon_t(Q) \).

1The power constraint is only defined on the intended signal, although distortions also contribute a small amount of power. However, this extra power is fully characterized by the SNR, \( P \), and we therefore assume that \( P \) is selected to make the total power usage fulfill all external system constraints.
between antennas can describe each individual subcarrier. However, there is some distortion-leakage between subcarriers and for simplicity we model this on a subcarrier basis as leakage between the antennas (the impact of what is done on the different antenna at one subcarrier is likely to average out when having many subcarriers). To capture a range of cases we propose

\[ v_n(Q) = \kappa^2 \left( (1-\alpha)q_n + \frac{\alpha}{N_t} \right) \tag{3} \]

where the parameter \( \alpha \in [0, 1] \) enables transition from one \((\alpha = 0)\) to many \((\alpha = 1)\) subcarriers. The parameter \( \kappa > 0 \) is the level of impairments\(^1\) This model is a good characterization of phase noise and IQ-imbalance, while amplifier non-linearities (that make \( v_n(Q) \) increase with \( P \)) are neglected \(^6\)—the dynamic range is assumed to always match the output power.

III. ANALYSIS OF CHANNEL CAPACITY

The transmitter knows the channel distribution \( f_H \), while the receiver knows the realization \( \mathbb{H} \). The capacity of (2) is

\[ C_{N_t, N_r}(P) = \sup_{f_H : \text{tr}(|f_H|^x) = \text{tr}(Q) = 1} I(\mathbf{x}; \mathbf{y}, \mathbb{H}) \tag{4} \]

where \( f_H \) is the PDF of \( \mathbf{x} \) and \( I(\cdot, \cdot, \cdot) \) is conditional mutual information. Note that \( I(\mathbf{x}; \mathbf{y}, \mathbb{H}) = \mathbb{H} \{ I(\mathbf{x}; \mathbf{y}|\mathbb{H} = \mathbb{H}) \} \).

**Lemma 1.** The capacity \( C_{N_t, N_r}(P) \) can be expressed as

\[ \sup_{Q : \text{tr}(Q) = 1} \mathbb{E}_H \left\{ \log_2 \det(1 + PHQH^H(PHY,H^H + I)^{-1}) \right\} \tag{5} \]

and is achieved by \( \mathbf{x} \sim \mathcal{CN}(\mathbf{0}, Q) \) for some feasible \( Q \geq 0 \).

**Proof:** For any realization \( \mathbb{H} = \mathbb{H} \) and fixed \( P, Q \) is a classical MIMO channel but with the noise covariance \((PHY,H^H + I)\). Eq. \(5\) and the sufficiency of using a Gaussian distribution on \( \mathbf{x} \) then follows from \(1\).

Although the capacity expression in \(5\) appears similar to that of the classical MIMO channel in \(1\) and \(1\), it behaves very differently—particularly in the high-SNR regime.

**Theorem 1.** The asymptotic capacity limit \( C_{N_t, N_r}(\infty) = \lim_{P \to \infty} C_{N_t, N_r}(P) \) is finite and bounded as

\[ M \log_2 \left( 1 + \frac{1}{\kappa^2} \right) \leq C_{N_t, N_r}(\infty) \leq M \log_2 \left( 1 + \frac{N_r}{M} \right) \tag{6} \]

where \( M = \min(N_t, N_r) \). The lower bound is asymptotically achieved by \( Q = \frac{1}{M^2} \mathbf{I} \). The two bounds coincide if \( N_t = N_r \).

**Proof:** The proof is given in the appendix.

This theorem shows that physical MIMO systems have a finite capacity limit in the high-SNR regime—this is fundamentally different from the unbounded asymptotic capacity for ideal transceivers \(^1\). Furthermore, the bounds in \(6\) hold for any channel distribution and are only characterized by the number of antennas and the level of impairments \( \kappa \).

The bounds in \(6\) coincide for \( N_t \leq N_r \), while only the upper bound grows with the number of transmit antennas when

\[ N_t > N_r \]. Informally speaking, the lower and upper bounds are tight when the high-SNR capacity-achieving \( Q \) is isotropic in a subspace of size \( N_t \) and size \( \min(N_r, N_t) \), respectively. The following corollaries exemplify these extremes.

**Corollary 1.** Suppose the channel distribution is right-rotationally invariant (e.g., \( \mathbb{H} \sim \mathbb{H} \mathbf{U} \) for any unitary matrix \( \mathbf{U} \)). The capacity is achieved by \( Q = \frac{1}{N_t} \mathbf{I} \) for any \( P \) and \( \alpha \). The lower bound in \(6\) is asymptotically tight for any \( N_t \).

**Proof:** The right-rotationally invariant implies that the \( N_t \) dimensions of \( \mathbf{H} \mathbf{H}^H \) are isotropically distributed, thus the concavity of \( \mathbb{E} \{ \log \det(\mathbf{S}) \} \) makes an isotropic covariance matrix optimal. The lower bound in \(6\) is asymptotically tight as it is constructed using this isotropic covariance matrix.

This corollary covers Rayleigh fading channels that are uncorrelated at the transmit side, but also other channel distributions with isotropic spatial directivity at the transmitter.

The special case of a deterministic channel matrix enables stronger adaptivity of \( Q \) and achieves the upper bound in \(6\).

**Corollary 2.** Suppose \( \alpha = 1 \) and the channel \( \mathbf{H} \) is deterministic and full rank. Let \( \mathbf{H} \mathbf{H}^H = \mathbf{U}_M \Lambda_M \mathbf{U}_M^H \) denote a compact eigendecomposition where \( \Lambda_M = \text{diag}(\lambda_1, \ldots, \lambda_M) \) contains the non-zero eigenvalues and the semi-unitary \( \mathbf{U}_M \in \mathbb{C}^{N_t \times M} \) contains the corresponding eigenvectors. The capacity is

\[ C_{N_t, N_r}(P) = \sum_{i=1}^M \log_2 \left( 1 + \frac{\lambda_i d_i}{\lambda_i^2 N_t + 1} \right) \tag{7} \]

for \( d_i = [\mu - \frac{1}{N_t}]_+ \) where \( \mu \) is selected to make \( \sum_{i=1}^M d_i = 1 \). The capacity is achieved by \( Q = \mathbf{U}_M \text{diag}(d_1, \ldots, d_M) \mathbf{U}_M^H \). The upper bound in \(6\) is asymptotically tight for any \( N_t \).

**Proof:** The capacity-achieving \( Q \) is derived as in \(11\), using the Hadamard inequality. The capacity limit follows as \( Q = \frac{1}{M^2} \mathbf{U}_M \mathbf{U}_M^H \) achieves the upper bound.

Although the capacity behaves differently under impairments, the optimal waterfilling power allocation in Corollary 2 is the same as for ideal transceivers (also noted in \(7\)). When \( N_t \geq N_r \), the capacity limit \( M \log_2(1 + \frac{N_r}{M}) \) is improved by increasing \( N_t \), because a deterministic \( \mathbf{H} \) enables selective transmission in the \( N_t \) non-zero channel dimensions while the transmitter-distortion is isotropic over all \( N_t \) dimensions.

We conclude the analysis by elaborating on the fact that the lower bound in \(6\) is always asymptotically achievable.

**Corollary 3.** If the channel distribution \( f_h \) is unknown at the transmitter, the worst-case mutual information \( \min_{f_h} I(\mathbf{x}; \mathbf{y}, \mathbb{H}) \) is maximized by \( Q = \frac{1}{N_t} \mathbf{I} \) (for any \( \alpha \)) and approaches \( M \log_2(1 + \frac{1}{\kappa^2}) \) as \( P \to \infty \).

A. Numerical Illustrations

Consider a channel with \( N_t = N_r = 4 \) and varying SNR. Fig. 2 shows the average capacity over different deterministic channels, either generated synthetically with independent \( \mathcal{CN}(0,1) \)-entries or taken from the channel measurements in \(11\). The level of impairments is varied as \( \kappa \in \{0.05, 0.1\} \).

Ideal and physical transceivers behave similarly at low and medium SNRs in Fig. 2 but fundamentally different at high SNRs. While the ideal capacity grows unboundedly, the capacity with impairments approaches the capacity limit \( C_{4,4}(\infty) = \).
The difference between the uncorrelated synthetic channels and the realistically correlated measured channels vanishes asymptotically. Therefore, only the level of impairments, \( \kappa \), decides the capacity limit.

Next, we illustrate the case \( N_t \geq N_r \) and different \( \alpha \). Fig. 2 considers \( N_t \in \{4, 12\} \), while having \( N_r = 4 \), \( \kappa = 0.05 \), and two different channel distributions: deterministic (we average over independent \( \mathcal{CN}(0, 1) \)-entries) and uncorrelated Rayleigh fading. We show \( \alpha \in \{0, 1\} \) in the deterministic case, while the random case gives \( Q = \frac{1}{N_t} I \) and same capacity for any \( \alpha \).

These channels perform similarly and have the same capacity limit when \( N_t = 4 \). The convergence to the capacity limit is improved for the random distribution when \( N_t \) increases, but the value of the limit is unchanged. Contrary, the capacity limits in the deterministic cases increase with \( N_t \) (and with \( \alpha \) since it makes the distortion more isotropic). Fig. 3 shows that there is a medium SNR range where the capacity exhibits roughly the same \( M \)-slope as achieved asymptotically for ideal transceivers. Following the terminology of [3], this is the degrees-of-freedom (DoF) regime while the high-SNR regime is the saturation regime; see Fig. 3. This behavior appeared in [5] for large cellular networks due to limited coherence time, but we demonstrate its existence for any physical MIMO channel (regardless of size) due to transceiver impairments.

### IV. GAIN OF MULTIPLEXING

The MIMO capacity with ideal transceivers behaves as \( M \log_2(1 + \frac{P}{N_t}) + \mathcal{O}(1) \) [1], thus it grows unboundedly in the high-SNR regime and scales linearly with the so-called multiplexing gain \( M = \min(N_t, N_r) \). On the contrary, Theorem 1 shows that the capacity of physical MIMO channels has a finite upper bound, giving a very different multiplexing gain:

\[
M^{\text{classic}} = \lim_{P \to \infty} \frac{C_{N_t, N_r}(P)}{\log_2(P)} = 0. \tag{8}
\]

In view of (8), one might think that the existence of a non-zero multiplexing gain is merely an artifact of ignoring the transceiver impairments that always appear in practice. However, the problem lies in the classical definition, because also physical systems can gain in capacity from employing multiple antennas and utilizing spatial multiplexing. A practically more relevant measure is the relative capacity improvement (at a finite \( P \)) of an \( N_t \times N_r \) MIMO channel over the corresponding single-input single-output (SISO) channel.

**Definition 1.** The finite-SNR multiplexing gain, \( M(P) \), is the ratio of MIMO to SISO capacity at a given \( P \). For (2) we get

\[
M(P) = \frac{C_{N_t, N_r}(P)}{C_{1,1}(P)}. \tag{9}
\]

This ratio between the MIMO and SISO capacity quantifies the exact gain of multiplexing. The concept of a finite-SNR multiplexing gain was introduced in [12] for ideal transceivers, while the refined Definition 1 can be applied to any channel model. The asymptotic behavior of \( M(P) \) is as follows.

**Theorem 2.** Let \( h \) denote the SISO channel. The finite-SNR multiplexing gain, \( M(P) \), for (2) and any \( \alpha \) satisfies

\[
\mathbb{E}\{||h||^2_F\} \leq \lim_{P \to 0} M(P) \leq \mathbb{E}\{||h||^2_2\}, \tag{10}
\]

\[
M \leq \lim_{P \to \infty} M(P) \leq \frac{\log_2(1 + \frac{N_r}{N_t})}{\log_2(1 + \frac{1}{\kappa})}, \tag{11}
\]

where \( \cdot \|_F \) and \( \cdot \|_2 \) denote the Frobenius and spectral norm, respectively. The upper bounds are achieved for deterministic channels (with full rank and \( \alpha = 1 \)). The lower bounds are achieved for right-rotationally invariant channel distributions.

**Proof:** The low-SNR behavior is achieved by Taylor approximation: \( Q = \frac{1}{N_t} I \) gives the lower bound, while the per-realization-optimal \( Q = uu^H \) (where \( u \) is the dominating eigenvector of \( H^H H \)) gives the upper bound. The high-SNR behavior follows from Theorem 1 and its corollaries.

This theorem indicates that transceiver impairments have little impact on the relative MIMO gain, which is a very positive result for practical applications. The low-SNR behavior in (10) is the same as for ideal transceivers (since \( P \mathbf{Y}_t \mathbf{H}^H + I \approx I \)), while (11) shows that physical MIMO channels can achieve \( M(P) > M \) in the high-SNR regime (although ideal transceivers only can achieve \( M(P) = M \)).

**A. Numerical Illustrations**

The finite-SNR multiplexing gain is shown in Figs. 4 and 5 for uncorrelated Rayleigh fading and deterministic channels, respectively, with \( N_t \in \{4, 8, 12\} \), \( N_r = 4 \), \( \kappa = 0.05 \), \( \alpha = 1 \).

The limits in Theorem 2 are confirmed by the simulations. Although the capacity behavior is fundamentally different for...
As a preliminary, consider any full-rank channel realization $\mathbf{H}$. Let $\mathbf{H}^H \mathbf{H} = \mathbf{U}_M \mathbf{A}_M \mathbf{U}_M^H$ denote a compact eigendecomposition (with $\mathbf{U}_M \in \mathbb{C}^{N_t \times M}$, $\mathbf{A}_M \in \mathbb{C}^{M \times M}$; see Corollary 2). The mutual information is increasing in $P$ and satisfies

$$\log_2 \det \left( \mathbf{I} + P \mathbf{H} \mathbf{Q} \mathbf{H}^H \left( \mathbf{P} \mathbf{Y} \mathbf{H}^H + \mathbf{I} \right)^{-1} \right) = \log_2 \det \left( \mathbf{I} + P \mathbf{U}_M^H \mathbf{Y}_t \mathbf{U}_M \mathbf{A}_M \right)$$

$$\log_2 \det \left( \mathbf{U}_M^H \left( \mathbf{Q} + \mathbf{Y}_t \right) \mathbf{U}_M \mathbf{A}_M \right) - \log_2 \det \left( \mathbf{U}_M^H \mathbf{Y}_t \mathbf{U}_M \mathbf{A}_M \right) = \log_2 \det \left( \mathbf{I} + \mathbf{U}_M^H \mathbf{Q} \mathbf{U}_M \left( \mathbf{U}_M^H \mathbf{Y}_t \mathbf{U}_M \right)^{-1} \right)$$

$$= \log_2 \det \left( \mathbf{I} + \mathbf{Y}_t^{-1/2} \mathbf{Q} \mathbf{Y}_t^{-1/2} \mathbf{U}_M^H \mathbf{U}_M \right) = \sum_{i=1}^{M} \log_2 \left( 1 + \mu_i \left( \mathbf{Y}_t^{-1/2} \mathbf{Q} \mathbf{Y}_t^{-1/2} \mathbf{U}_M^H \mathbf{U}_M \right) \right) \quad (13)$$

as $P \to \infty$. The first equality follows from expanding the logarithm and using the rule $\det(\mathbf{I} + \mathbf{A} \mathbf{B}) = \det(\mathbf{I} + \mathbf{B} \mathbf{A})$. This enables the limit $P \to \infty$ and achieves an expression where the impact of $\mathbf{A}_M$ cancels out. We then identify the projection matrix $\mathbf{U}_M^H \mathbf{U}_M = \mathbf{Y}_t^{-1/2} \mathbf{U}_M \left( \mathbf{U}_M^H \mathbf{Y}_t \mathbf{U}_M \right)^{-1} \mathbf{U}_M^H$ onto $\mathbf{U}_M^H \mathbf{Y}_t^{1/2}$. The $r$th strongest eigenvalue is denoted $\mu_r(\cdot)$.

The convergence as $P \to \infty$ is uniform, thus we can achieve bounds by showing that all realizations has the same asymptotic bound. A lower bound is given by any feasible $\mathbf{Q}$; we select $\mathbf{Q} = \frac{1}{N_t} \mathbf{I}$ as it gives $\mathbf{Y}_t = \frac{P}{N_t} \mathbf{I}$ and makes (12) independent of $\mathbf{H}$. Since (13) is a Schur-concave function in the eigenvalues, an upper bound is achieved by replacing $\mu_r(\cdot)$ with the average eigenvalue $\frac{1}{M} \text{tr} \left( \mathbf{Y}_t^{-1/2} \mathbf{Q} \mathbf{Y}_t^{-1/2} \mathbf{U}_M^H \mathbf{U}_M \right) = \frac{1}{M} \text{tr} \left( \mathbf{Y}_t^{-1/2} \mathbf{Q} \mathbf{Y}_t^{-1/2} \mathbf{U}_M^H \mathbf{U}_M \right)$, where the inequality follows from removing the projection matrix (since $\mathbf{U}_M^H \mathbf{U}_M \preceq \mathbf{I}$). Note that the upper and lower bounds coincide when $N_t \leq N_r$, thus $\mathbf{Q} = \frac{1}{M} \mathbf{I}$ is asymptotically optimal in this case.

**References**


